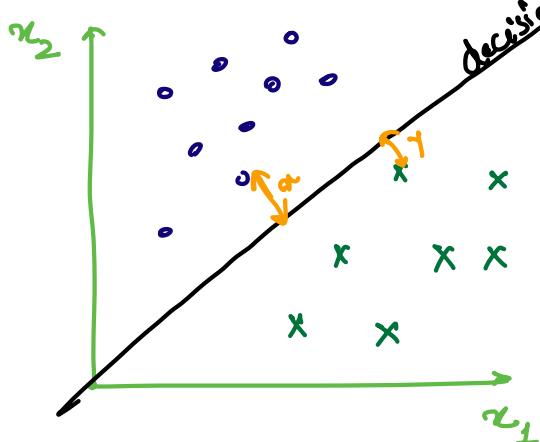


# SVM (Support Vector Machine)

Classification Algo

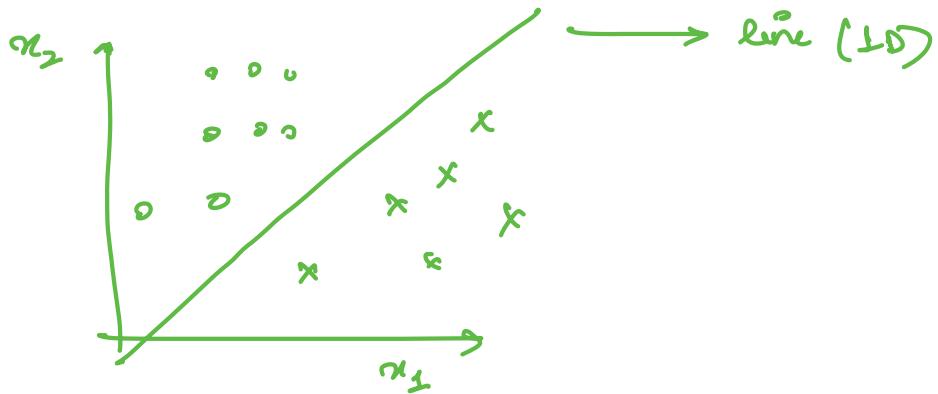


Points which are closest to your decision boundary should be very far away from each other.

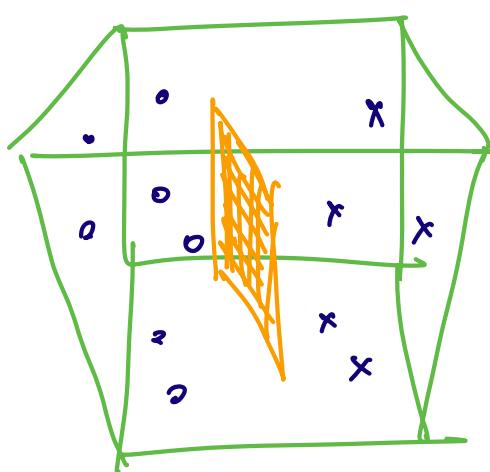
Hypap line:

n features

hyperplane n-1 dimension

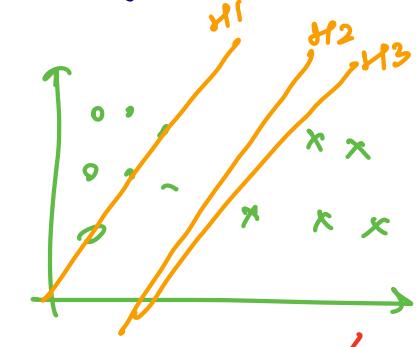


3 features

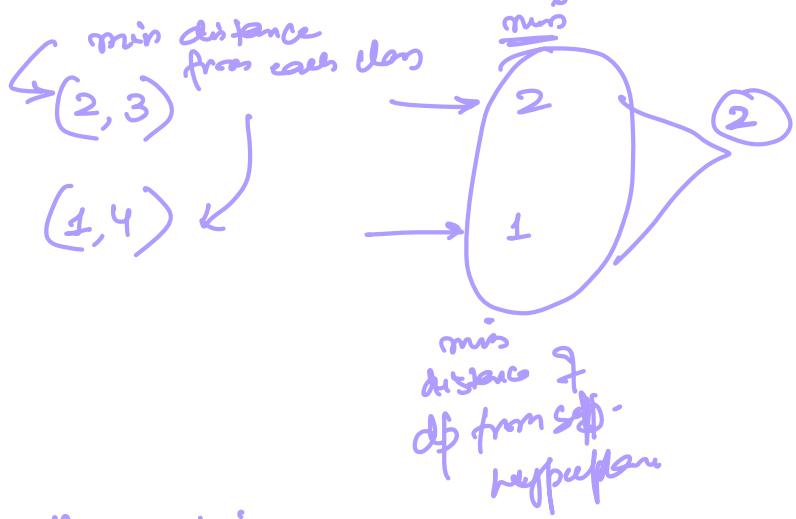
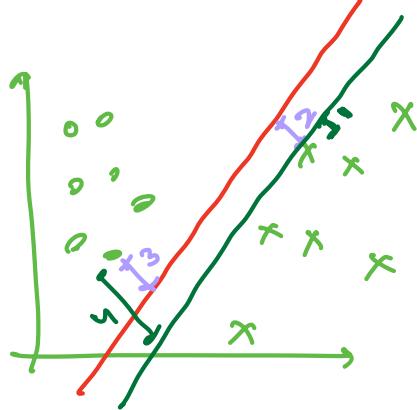


2D hyperplane: plane

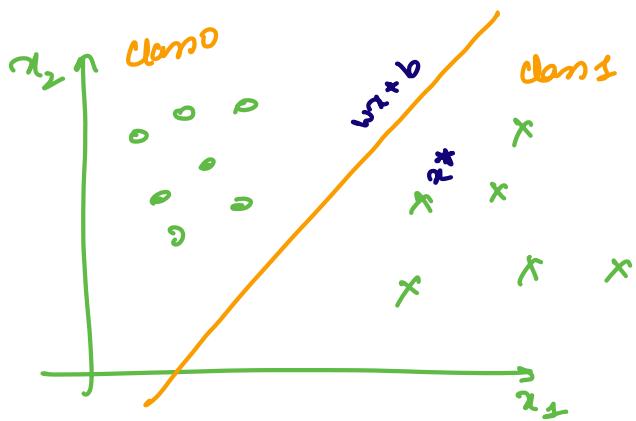
## Separating Hyperplane:



$H_2, H_3 \rightarrow$  Separating Hyperplane  
 $H_1 X$



maximize the minimum  
distance from sh-



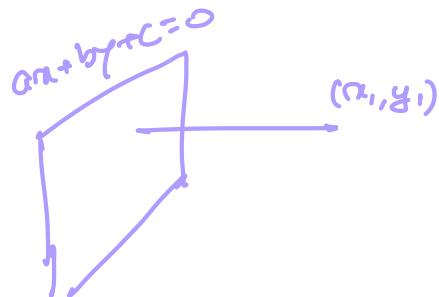
$$y = mx + b$$

$$y = w \cdot x + b$$

$$w \cdot x^* + b$$

$$w \cdot x^* + b > 0 \quad \text{class 1}$$

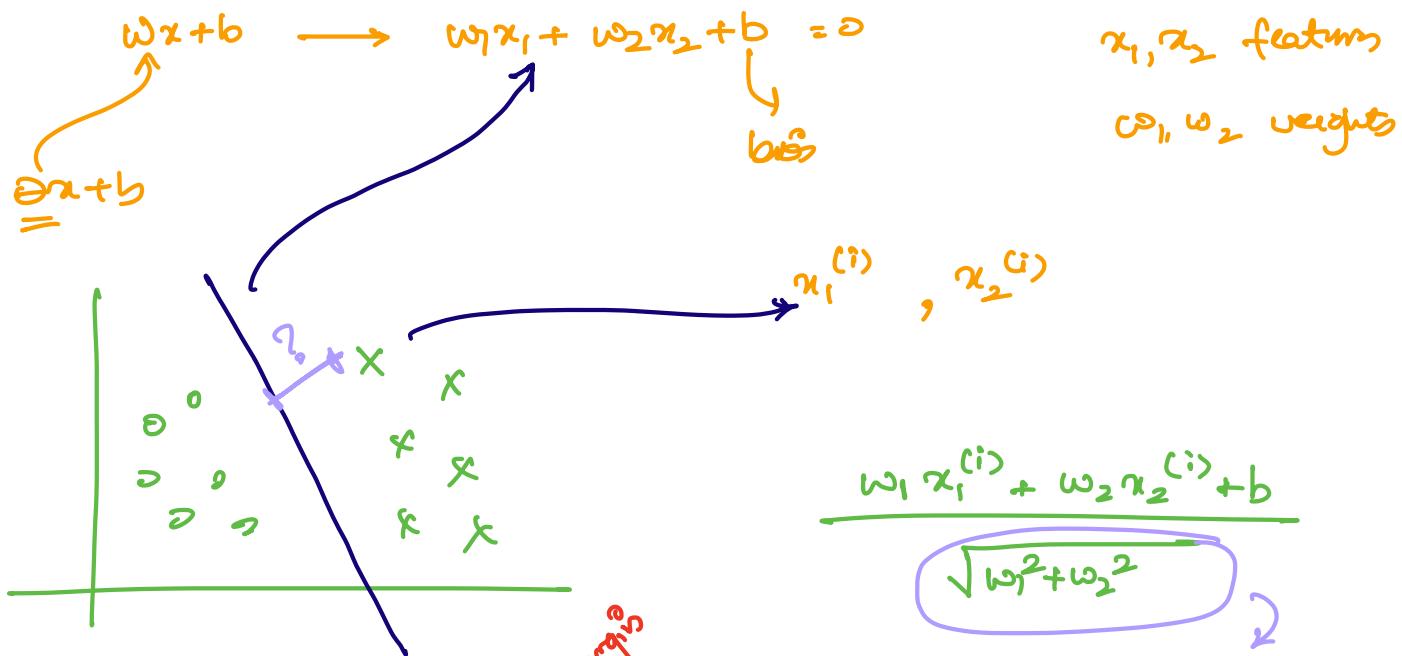
$$w \cdot x^* + b \leq 0 \quad \text{class 0}$$



$$\frac{ax_1 + bx_2 + c}{\sqrt{a^2 + b^2}}$$

$L_1$  norm:  $(|a| + |b|)^{x_1}$   
 $L_2$  norm:  $(a^2 + b^2)^{x_2}$

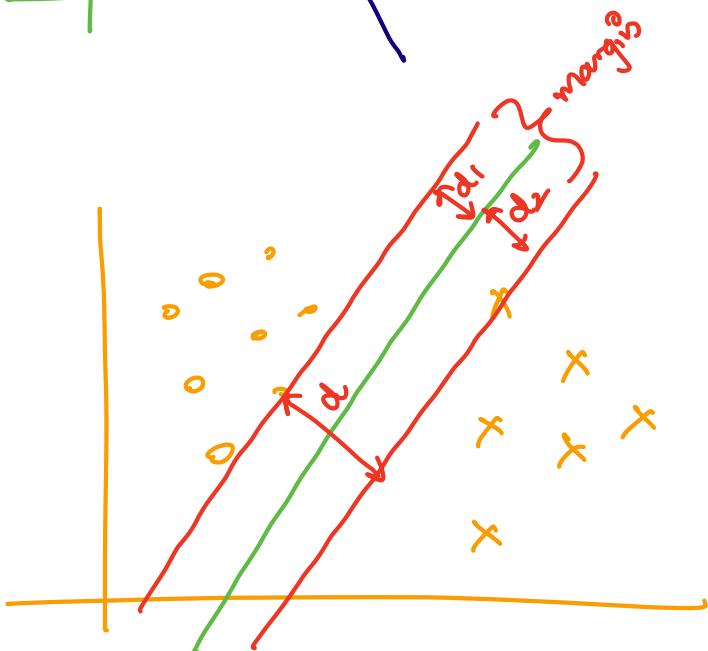
$$L_3 \text{ norm} \quad (a^3 + b^3)^{\frac{1}{3}}$$



$$\frac{w_1 x_1^{(i)} + w_2 x_2^{(i)} + b}{\sqrt{w_1^2 + w_2^2}}$$

$\hookrightarrow$  norm

$\|w\|_2$



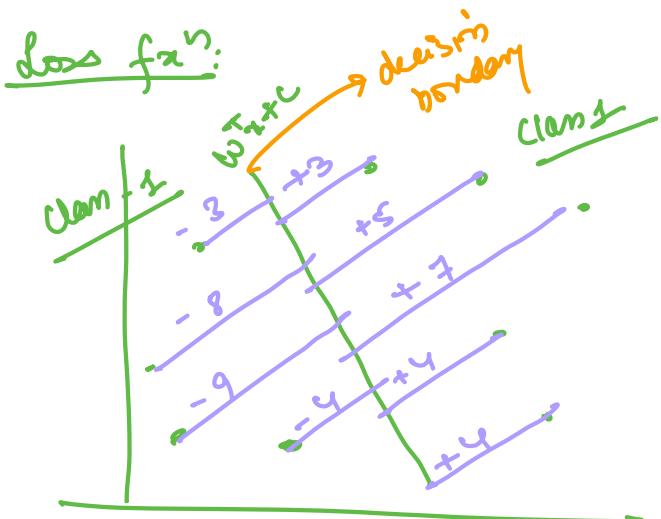
formulating objective:

$$X = \{x^1, x^2, \dots, x^m\}$$

$$Y = \{y^1, y^2, \dots, y^m\}$$

Binary Classification  $y^{(i)} \in \{-1, +1\}$

$\hookrightarrow$  class labels



$$\gamma^{(i)} = \frac{w^T x^{(i)} + b}{\|w\|_2}$$

distance of iter point from decision boundary

$$\gamma = \min_{i=1 \dots m} \gamma^{(i)}$$

(3)

target: max  $\gamma$

SVM Objective

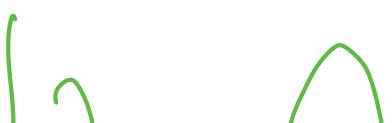
[ max  $\gamma$   
such that  $\frac{\gamma^{(i)}(w^T x^{(i)} + b)}{\|w\|} \geq \gamma$  for all  $i = 1 \dots m$  ]

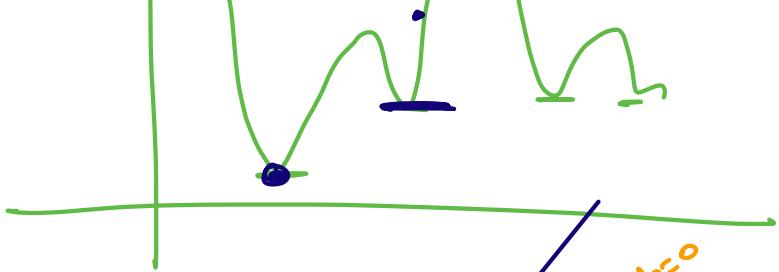
$$\frac{w^T x^{(i)} + b}{\|w\|_2} \rightarrow \text{normalized distance}$$

↑  
↓

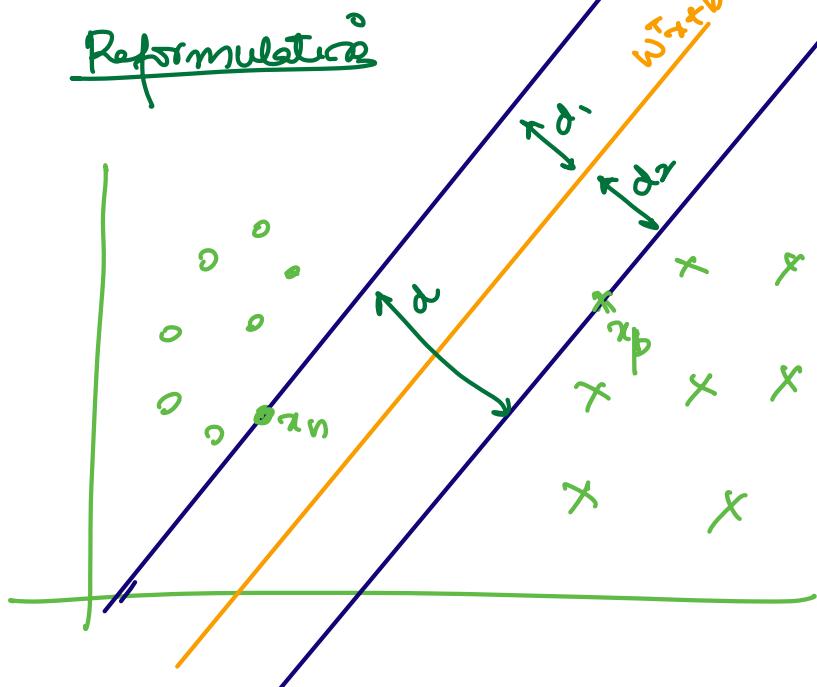
$$\gamma^{(i)} \frac{w^T x^{(i)} + b}{\|w\|_2} \rightarrow \text{normalized absolute distance}$$

SVM Objective  $\rightarrow$  non convex





Reformulation



Re-normalize our data points such that point which is closest to hyperplane lies at distance +1, -1

$$d_1 = \frac{|\omega^T x_n + b|}{\|\omega\|_2}$$

$$\omega^T x_n + b = -1$$

$$d_2 = \frac{|\omega^T x_p + b|}{\|\omega\|_2}$$

$$\omega^T x_p + b = 1$$

$$d_1 = \frac{1}{\|\omega\|_2}$$

$$d_2 = \frac{1}{\|\omega\|_2}$$

$$d = d_1 + d_2 = \frac{2}{\|\omega\|_2}$$

$$\max d \Rightarrow \min \frac{\|\omega\|_2}{2}$$

SVM  
objective:

$$\min \frac{\|\omega\|_2}{2}$$

under the condition that all points should

have max distance 1.

$$\frac{y^{(i)}(\omega^T x^{(i)} + b)}{\|\omega\|_2} \geq \frac{1}{\|\omega\|_2}$$

$$d_1 = \frac{1}{\|\omega\|_2}$$

svm  
objectiv:

$$\begin{bmatrix} \min \frac{\|\omega\|}{2} \\ \text{such that } y^{(i)}(\omega^T x^{(i)} + b) \geq 1 \end{bmatrix}$$

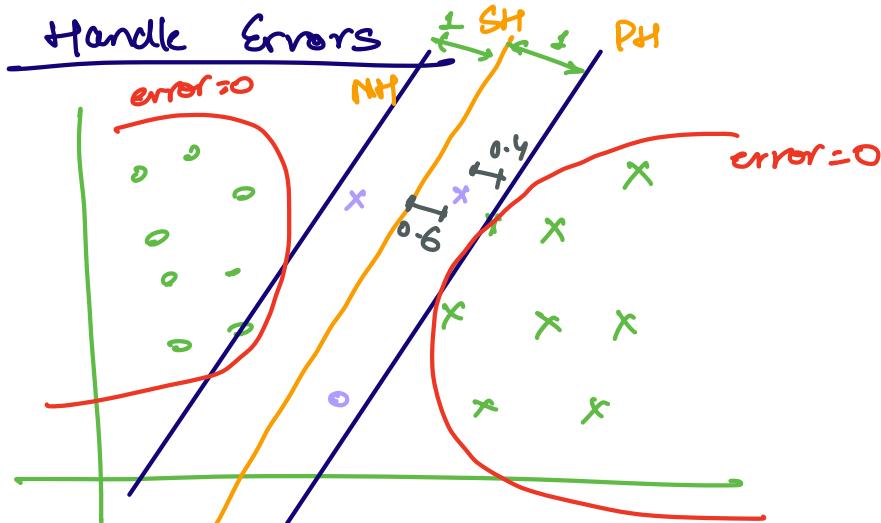
$$\|\omega\|_2 = \sqrt{\omega_1^2 + \omega_2^2}$$

$$\begin{aligned} \|\omega\|_2^2 &= \omega_1^2 + \omega_2^2 = \omega \cdot \omega^T \\ &\xrightarrow{\text{differentiation}} 2\omega_1 + 2\omega_2 = 0 \\ &\quad \omega_1 + \omega_2 = 0 \end{aligned}$$

$$\begin{aligned} \omega^T \omega &= [\omega_1 \omega_2 \dots \omega_n] \begin{bmatrix} \omega \\ \omega_1 \\ \omega_2 \\ \vdots \\ \omega_n \end{bmatrix} \\ &= \omega_1^2 + \omega_2^2 + \dots + \omega_n^2 \end{aligned}$$

svm  
objectiv:

$$\begin{bmatrix} \min \frac{\|\omega\|_2^2}{2} \\ \text{such that } y^{(i)}(\omega^T x^{(i)} + b) \geq 1 \\ \forall i \in \{1, \dots, m\} \end{bmatrix}$$



$\epsilon^{(i)}$  denotes the distance of the point from the hyperplane

$$SM \leftarrow \underbrace{y^{(i)}(\omega^T x^{(i)} + b)}_{\geq 1} \geq 1$$

$$y^{(i)}(\omega^T x^{(i)} + b) \geq \underbrace{1 - \varepsilon^{(i)}}_{0.6} \rightarrow 0.4$$

Allowing some errors

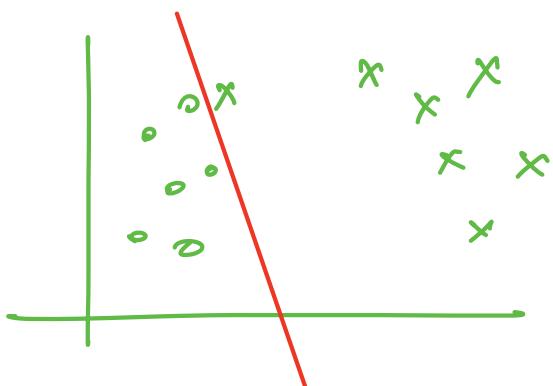
$$\text{Loss : } \min_{\omega} \frac{1}{2} \omega^T \omega + C \sum_{i=1}^m \varepsilon^{(i)}$$

$$\text{such that } y^{(i)}(\omega^T x^{(i)} + b) \geq 1 - \varepsilon^{(i)}$$

$C$  = hyperparameter

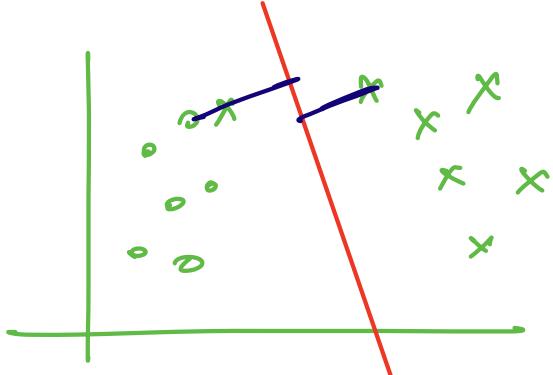
$C = \infty$  No errors

$$\min_{\omega} \frac{1}{2} \omega^T \omega + \frac{1000}{m} \sum_{i=1}^m \varepsilon^{(i)}$$



You will not be able to achieve maximum margin hyperplane.

$C = 1$  afford some errors, maximum margin sep. hyperplane

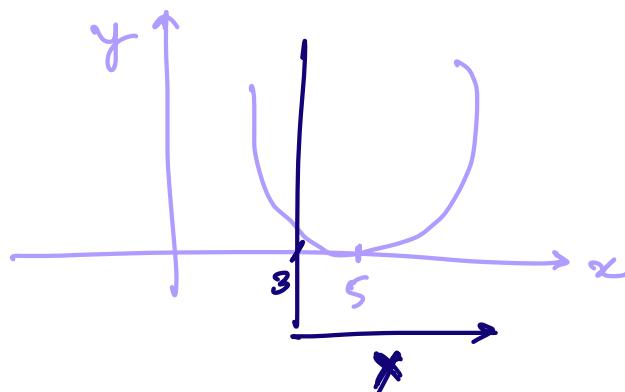


Non Convex



distance = L

$$y = (x-5)^2$$



value of  $x$  for which  $y$  is min?

$$\leq$$

such that  $x \leq 3$  constraint

Remove linear constraints

loss :  $\min \frac{1}{2} \omega^T \omega + C \sum_{i=1}^m \varepsilon^{(i)}$

such that  $y^{(i)}(\omega^T x^{(i)} + b) \geq 1 - \varepsilon^{(i)}$

Convex fn<sup>w</sup>  
constraints :  
we want  
non linear  
constraints.

$$\varepsilon^{(i)} \geq 1 - y^{(i)}(\omega^T x^{(i)} + b)$$

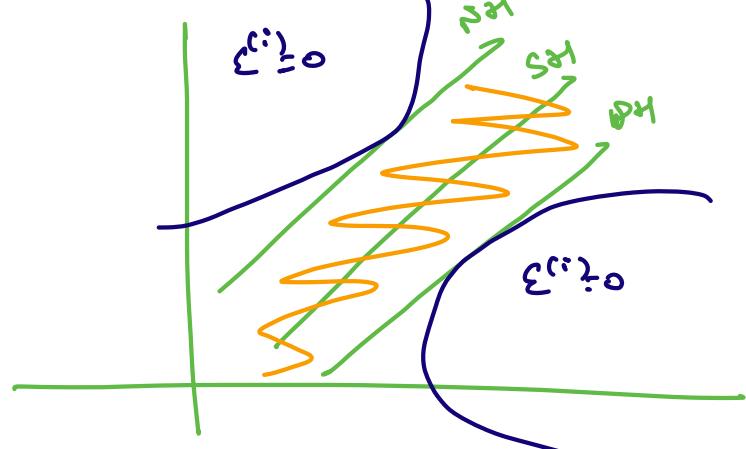
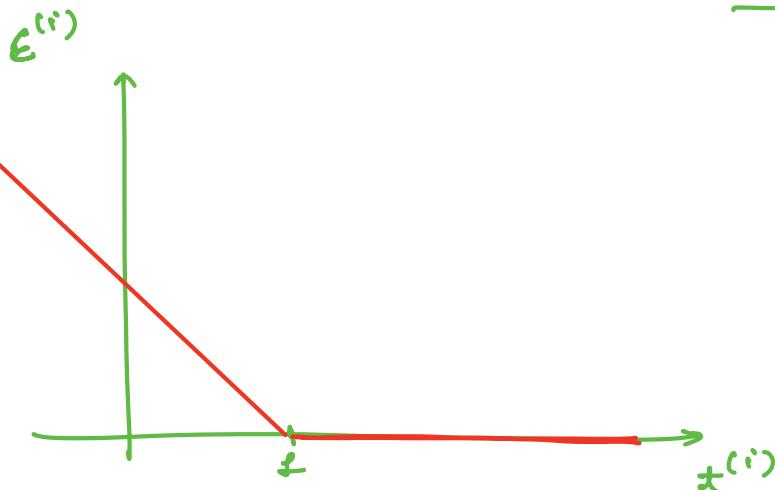
$t^{(i)}$   
unnormalized  
absolute distance  
of  $x^{(i)}$  from SR.

$$\varepsilon^{(i)} \geq 1 - t^{(i)}$$

$$\varepsilon^{(i)} > 0$$

↓ combine

$$\varepsilon^{(i)} = \max(0, 1 - \hat{x}^{(i)})$$



for differentiating  $\varepsilon^{(i)}$   
concept of subgradient

$$\begin{cases} 0 & t_i \geq 1 \\ -1 & t_i < 1 \end{cases}$$

$$L = \frac{1}{2} \mathbf{w}^T \mathbf{w} + C \sum_{i=1}^m \max(0, 1 - \hat{x}^{(i)})$$

$$\text{where } \hat{x}^{(i)} = y^{(i)} (\mathbf{w}^T \mathbf{x}^{(i)} + b)$$

SVM objective

Random value of  $\mathbf{w}$

How good present  $\mathbf{w}$ ?

Update  $\mathbf{w}$ 's  
Gradient Descent

$$\mathbf{w} = \mathbf{w} - \eta \left( \frac{\partial L}{\partial \mathbf{w}} \right) \quad ?$$

$$\mathbf{w} = \begin{bmatrix} w_1 \\ w_2 \\ w_3 \\ w_4 \\ \vdots \end{bmatrix} \quad \mathbf{w}^T = [w_1 \ w_2 \dots]$$

$$\mathbf{w}^T \cdot \mathbf{w} = [w_1 \ w_2 \dots \ w_n]$$

$$= w_1^2 + w_2^2 + \dots + w_n^2$$

$$= \| \mathbf{w} \|_2^2$$

$$b = b - \eta \left( \frac{\partial L}{\partial b} \right) ?$$

$$\frac{1}{2} \omega^T \cdot \omega = \frac{1}{2} (\omega_1^2 + \omega_2^2 + \dots + \omega_n^2)$$

$$\frac{\partial}{\partial \omega} \left( \frac{1}{2} \omega^T \cdot \omega \right) = \frac{1}{2} (2\omega_1 + 2\omega_2 + \dots + 2\omega_n)$$

$$= (\omega_1 + \omega_2 + \dots + \omega_n) = \omega$$

$$\frac{\partial L}{\partial \omega} = \omega + c \sum_{i=1}^m \frac{\partial}{\partial \omega} \left( \max(0, 1 - x^{(i)}) \right)$$

$$\frac{\partial f}{\partial \omega} = \frac{\partial f}{\partial x} \cdot \frac{\partial x}{\partial \omega}$$

$$\frac{\partial L}{\partial \omega} = \omega + c \sum_{i=1}^m \frac{\partial f}{\partial x^{(i)}} \cdot \frac{\partial x^{(i)}}{\partial \omega}$$

$$= \omega + c \sum_{i=1}^m \frac{\partial}{\partial x^{(i)}} \left( \max(0, 1 - x^{(i)}) \right) \cdot \frac{\partial x^{(i)}}{\partial \omega}$$

$$= \omega + c \sum_{i=1}^m \begin{cases} 0 & \text{if } x^{(i)} \geq 1 \\ -1 & \text{if } x^{(i)} < 1 \end{cases} \frac{\partial x^{(i)}}{\partial \omega}$$

$$x^{(i)} = y^{(i)} (\omega^T x^{(i)} + b)$$

$$\frac{\partial x^{(i)}}{\partial \omega_j} = y^{(i)} x^{(i)}$$

$$\frac{\partial L}{\partial \omega} = \omega + c \sum_{i=1}^m \begin{cases} 0 & \text{if } f^{(i)} > 1 \\ -1 & \text{if } f^{(i)} < 1 \end{cases} y^{(i)} x^{(i)}$$

$$b = b - \gamma \left( \frac{\partial L}{\partial b} \right) ?$$

$$\frac{\partial L}{\partial b} = 0 + c \sum_{i=1}^m \frac{\partial}{\partial b} \underbrace{[\max(0, 1-f_i)]}_f$$

$$\frac{\partial L}{\partial b} = c \sum_{i=1}^m \frac{\partial f}{\partial x_i} \cdot \frac{\partial x^{(i)}}{\partial b}$$

$$\frac{\partial L}{\partial b} = c \sum_{i=1}^m \begin{cases} 0 & \text{if } f^{(i)} > 1 \\ -1 & \text{if } f^{(i)} < 1 \end{cases} \frac{\partial f^{(i)}}{\partial b}$$

↓

$$\frac{\partial f^{(i)}}{\partial b} = \frac{\partial}{\partial b} (y^{(i)} (\omega^\top x^{(i)} + b))$$

$$= y^{(i)}$$

$$\frac{\partial L}{\partial b} = c \sum_{i=1}^m \begin{cases} 0 & \text{if } f^{(i)} > 1 \\ -1 & \text{if } f^{(i)} < 1 \end{cases} y^{(i)}$$

UPDATE RULES:

$$\omega = \omega - \eta \left[ \omega + c \sum_{i=1}^m \begin{cases} 0 & \text{if } x^{(i)} \geq 1 \\ -1 & \text{if } x^{(i)} < 1 \end{cases} y^{(i)} x^{(i)} \right]$$

$$\omega = \omega - \eta \omega + \sum_{i=1}^m \begin{cases} 0 & \text{if } x^{(i)} \geq 1 \\ \eta c y^{(i)} x^{(i)} & \text{if } x^{(i)} < 1 \end{cases}$$

$$b = b - \left( \eta c \sum_{i=1}^m \begin{cases} 0 & \text{if } x^{(i)} \geq 1 \\ -1 & \text{if } x^{(i)} < 1 \end{cases} y^{(i)} \right)$$

$$b = b + \sum_{i=1}^m \begin{cases} 0 & \text{if } x^{(i)} \geq 1 \\ \eta c y^{(i)} & \text{if } x^{(i)} < 1 \end{cases}$$